

Heating Radiator Thermostat MLR003RiEU61-07-1.1 LoRaWAN CLASS A EU868MHz SF7BW125 User Manual and Device Specification



The Micropelt MLR003R product series has been designed for use with heating radiators and M30x1,5 valve thread. LoRaWAN allows to control heating radiators over long distances, even inside buildings. Significant cost savings on labor and material cost for wiring, network infrastructure, building structural changes will reduced the amortization time over conventional systems while installing the system is only a matter of days.

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1 Revision History MLR003RiEU61-07-1.1

Rev.-No.	Description of Revision	Revised by	Date
	<p>v8e has been derived from the Micropelt technology platform description v7e.</p> <p>Changed name to MLR003.</p> <p>Document describes the first release of MLR003.</p> <p>Most recent changed against the general-purpose platform description.</p>		
v8e	<ul style="list-style-type: none"> Removed Summer mode Added 480min RF CI in Payload Added temperature offset for valve- and ambient-sensor. Added harvesting halt during radio communication. 	Schmidt/ Volkert	Jan. 21, 2021
v10e	<ul style="list-style-type: none"> Change product name to MLR003 General update on description and user guide 	Volkert	Jun. 21, 2021
v11e	<p>Change downlink payload</p> <p>Added Label spec.</p>	Couzens Volkert	Jun. 22, 2021
v12e	<p>Change Activating from Mounting Position operating flow diagram</p> <p>Changed front page picture of MLR003</p>	Couzens Volkert	Aug. 04, 2021 Aug. 20, 2021
v13e	<p>Full document review</p> <p>Update cover page, headlines, added sect. 7.2</p>	Couzens Volkert	Sept. 22, 2021 Sept. 23, 2021
v14e	<p>Adjust speaker beeping communication in user interface</p> <p>Added SF7BW125 to front page</p> <p>Removed downlink “reserved” bytes 7 and 8</p> <p>Added picture of MLR003-KEY</p>	Couzens Volkert	Sept. 28, 2021 Oct. 11, 2021

V15e	<p>Added clauses and information required by product safety, EN60335-1:2012.</p> <p>Described the position of the labels</p> <p>Corrected distortion of “CE”-print on product label</p>	Schmidt	Nov. 05, 2021
V16e	<p>Added certification details</p> <p>Added contact email devicecredentials@micropelt.com</p> <p>Corrected NFC-Tag label (16.2)</p>	Volkert	Nov 19, 2021
v17e	<p>Update from Rev1.0 to Rev1.1:</p> <ul style="list-style-type: none"> • Extend Uplink payload to include User Mod and User Value • Extend motor Reference Run travel distance <p>Added declaration of conformity (CE)</p>	Couzens Volkert	Jan. 24, 2022
	Added new section 09.11 Battery Charging Flow Chart	Bala	Feb 16, 2022
	Changed product name and article number to MLR003RiEU61-07-1.1	Volkert	Feb 23, 2022

2 Use and Safety MLR003R

Use and safety instructions:

This appliance is not intended for use by persons (including children) with reduced physical, sensory or mental capabilities, or a lack of experience and knowledge, unless they have been given supervision or instruction concerning the use of the device by a person responsible for their safety.

- This product is not a toy. Children shall be advised to refrain from playing with it.
- The metallic part of the unit's housing serves as a heat sink. Be sure that the air circulation around it is not obstructed by furniture, curtains, plants, or any other object.
- If the device has been stored in a cold environment, make sure that it resumes close to room temperature before use. This is to prevent damaging due to condensation.
- The thermostatic head is designed for indoor use only. Do not allow the thermostatic head to get wet. Its sensitive electronics can be affected.
- The unit is best cleaned with a dry or slightly damp cloth. Do not use aggressive cleaning agents or solvents.
- Refrain from exposing the unit to environmental stress such as high mechanical forces (do not step on it), strong vibrations, direct sunlight or extreme temperatures.
- The unit must not be disassembled or modified. There are no user-serviceable parts inside.
- Be aware that correct operation can be affected by strong electromagnetic fields. Typical sources of such are mobile phones, 2-way radios, RC transmitters, microwave ovens, electric motors.
- The thermostatic head has been designed and must solely be used for the purpose of controlling a M30 x 1.5 circulation valve. Any other use may pose a hazard to the device itself, to the equipment involved, or to the health of the user.
- When operating the device in a workplace environment, be sure to observe the workplace regulations that may apply.

Intended use: The self-powered thermostatic head is suitable solely for controlling water-filled heating radiators. Any other use – including control of floor heating systems – is not permitted and can result in malfunctions or damage. Do not disassemble or modify any part of the product. It is important to comply with the safety notice included in these operating instructions.

In case of questions, please contact us:

<https://micropelt.atlassian.net/servicedesk/customer/portal/1>

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3 General Description MLR003R

This document defines the properties of Micropelt's maintenance free, intelligent thermostatic head MLR00RiEU61-07-1.1. This MLR003 is used for control of heating radiators with standard valve connection M30x1.5 (Section 10).

MLR00RiEU61-07-1.1 is an 868MHz LoRaWAN CLASS-A wireless actuator operating in SF7BW125. LoRaWAN end-devices of Class A allow for bidirectional communications whereby each end-device's uplink transmission is followed by two short downlink receive windows. The transmission slot scheduled by the end-device is based on its own communication needs with a small variation based on a random time basis (ALOHA-type of protocol). Class-A operation is the lowest power end-device system for applications that only require downlink communication from the server shortly after the end-device has sent an uplink transmission. Downlink communications from the server at any other time will have to wait until the next scheduled uplink. SF7 is using the shortest time-on-air to maximize the number of end nodes operating on one gateway.

Each standard production MLR00RiEU61-07-1.1 unit has a unique DEVEUI, APPEUI (JOINEUI) and a randomly generated APPKEY. Device credentials are secret and will only be submitted with the product delivery. Questions related to device credentials can be sent to devicecredentials@micropelt.com.

To operate the device, the unit must be paired with a compatible controller or gateway unit supporting its communication profile (Section 7). The pairing is done as described in Section 8.3. Once mounted and activated on the valve body using the magnetic key, a calibration cycle starts to automatically adapt itself to the individual valve. Then it is ready for use. Adapters are available for a majority of non-M30x1.5 valve bodies.

Success of activation or deactivation is signaled by tone signals and LED (Section 8.1).

The product is delivered in mounting position (off) with the valve plunger completely retracted. When operating, the unit recognizes if it is installed on a valve body by means of internal force and travel distance measurement. The device has built-in motor error detection "ME". The ME bit signals motor issues during normal operation.

The actuator operates with a communication profile as further specified in Section 11. The default radio communication cycle is 10 minutes. Installation, activation and a successful join with the network server will immediately set the radio communication interval to every 10 seconds for an installation period of 5 minutes to provide rapid feedback. Temperature values are transmitted in both raw and corrected temperature formats.

The actuator has a built-in, valve-side temperature sensor to determine the flow pipe temperature. A controllable offset of +5°C has been added to compensate for the temperature drop between the hot water and the sensor element located in the actuator's aluminum valve adapter.. The device transmits a variety of information to the control unit by sending an uplink (Section 7.1). The control unit responds by sending a downlink (Section 7.2).

The integrated valve side temperature sensor is also used for freeze protection. Freeze protection is activated at $\leq 6^{\circ}\text{C}$.

The ambient sensor is used to measure the room temperature. During heating operation, the ambient sensor is influenced by self-heating of the metallic device housing. The algorithm used to estimate the actual ambient temperature is described in Section 12.9.

Unsuccessful radio communication attempts are reported by status bit RCE. After 6 consecutive unsuccessful radio communication attempts (acknowledge from the gateway), the actuator automatically switches to the safety mode and safety values as specified by the user. In this situation, the radio communication period is increased to once every hour.

The actuator generates the required electrical energy for operation (motor, sensors, and radio communication) by means of a built-in thermoelectric generator (TEG) and therefore operates maintenance-free. It harvests energy from the temperature difference between the valve body heat and ambient temperature (usually room temperature). An additional energy source such as a primary battery or external power supply is not required. The internal energy storage device is charged upon delivery, so that sufficient energy is available for installation.

4 Operating Modes MLR003R

	Installation cycle	Standard operation	Idle state	Radio failure	Forced heating	Freeze Protection
Comments		Valve target % Or Room target temperature	Phases between monitoring and communicating	Transmit messages not received by the gateway	Valve opens to 50% (or remains in current position if current position is $\geq 50\%$)	Valve opens to 95%
Trigger	Magnetic switch. Join accept from Gateway, & Device is mounted	Internal timer	Internal timer	From activation: No Gateway connect from standard operation: 6 consecutive Gateway communication failures	Battery voltage $< 2V$	Flow sensor raw temperature $\leq 6^{\circ}C$
Radio communication interval (RCI)	10 seconds for 5 minutes	5 minutes 10 minutes 60 minutes 120 minutes 480 minutes	OFF	Three times 30 seconds Then once 2 minutes Then 60 minutes	OFF	OFF
Dynamic change of communication interval	No	Yes	No	No	No	No

Sensors (flow, ambient)	Active, every 10 seconds	Active	OFF	Active	OFF	Active, every 2 minutes
Freeze protection	Active, every 10 seconds	Active, every 150 seconds	OFF	Active, every 150 seconds	OFF	Active
Motor operation	Reference run. Then active, according to Radio Communica tion	Active, according to Radio Communica tion	OFF	Active	OFF	OFF
Monitoring of battery	Active, every 10 seconds	Active	OFF	Active	Active, every 12 hours	Active, every 2 minutes
Internal temperatu re controller	If User Mode is Set Point Ambient Temperatur e: active	If User Mode is Set Point Ambient Temperatur e: active	OFF	If Safety Mode is Set Point Ambient Temperatur e: active	OFF	OFF
Default upon activation and no downlinks	Setpoint ambient 20°C	Setpoint ambient 20°C		Setpoint ambient 20°C		

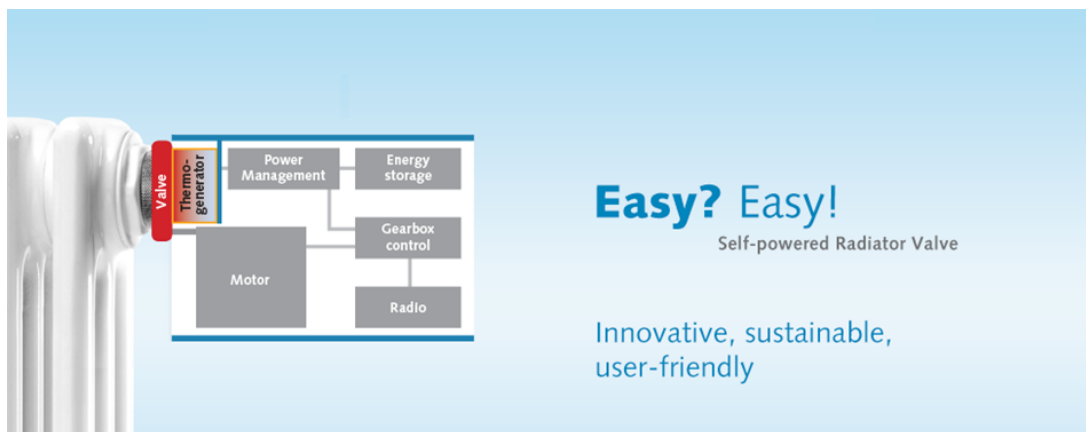
5 Power Consumption MLR003R

Function	Power consumption average current draw	Battery runtime w/o active harvesting @ 500mAh**
Mounting position	2.2 µA	25.9 years
Radio communication every 10 min. No motor = unheated room	n.n µA	n.n years
Radio communication every 10 min. Motor movement: Morning: Full open Throughout the day: 10% every 30 min. Evening: Full close Total: 400%	nn.n µA	n.n years

6 Power management MLR003R

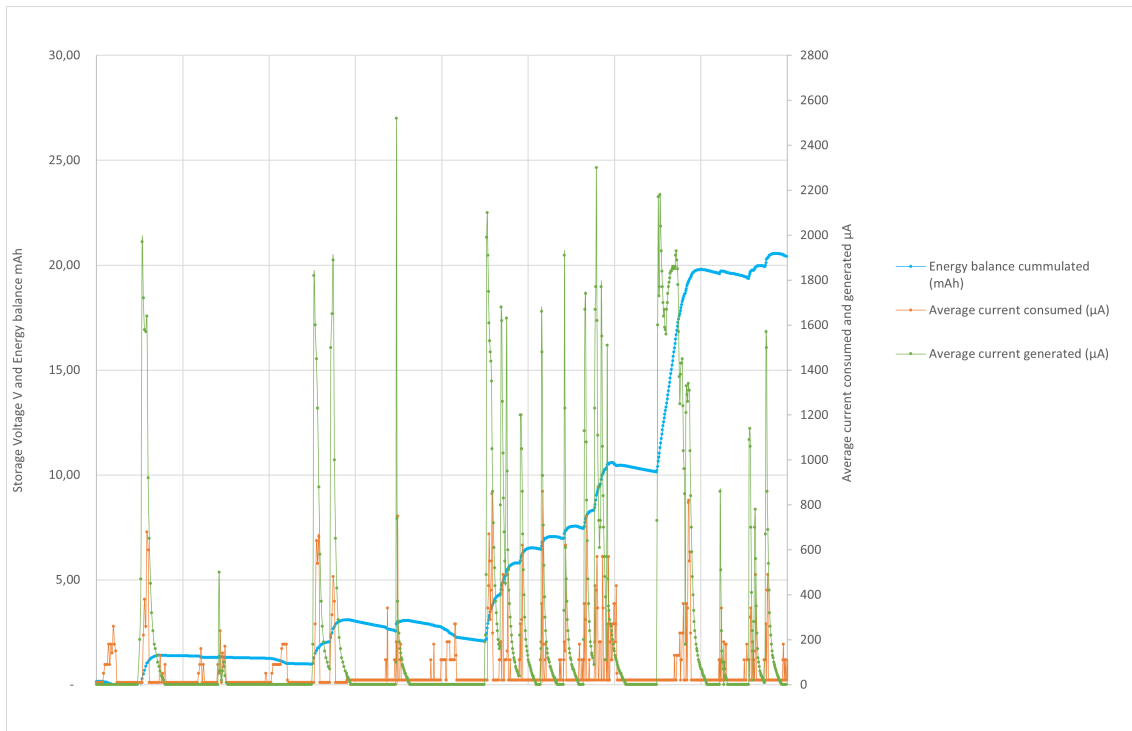
6.1 Energy Harvesting

The actuator obtains the electrical energy required for operation by means of a thermoelectric generator (TEG), from the temperature difference between the heating flow temperature and the room temperature. During active flow temperatures, excess energy is accumulated in the internal storage. The energy balance of the actuator is designed to allow operation through 366 days per year when used in typical circulation strands with hot water supply throughout the year. A lack of hot water operation as it occurs in down times or malfunctions inevitably leads to the internal storage being discharged, which means that permanent and normal operation of the device can no longer be guaranteed.

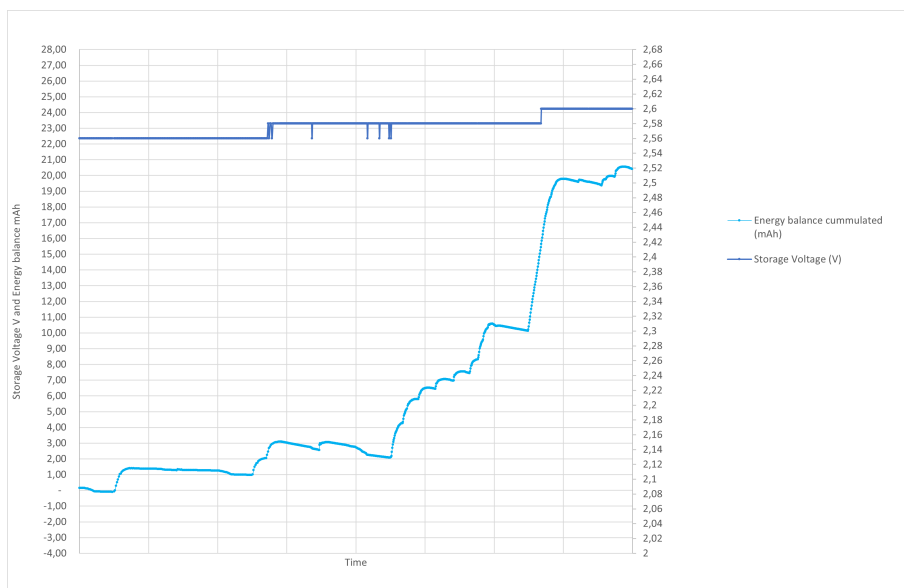


6.1.1 Device power management

MLR003RiEU61-07-1.1 allows the end user application to monitor and compute the energy status through regular measurement of the device internal parameters. Internal storage voltage STV (V) and average current generated ACG (μA) are actual measured values whereas average current consumed ACC (μA) is a computed value. The computed average current consumed value includes motor amount and direction of movement, radio communication frequency, and sleep current. The following two diagrams are illustrations of the energy balance from a running application.



1 Exemplary values for ACC, ACG and computed energy balance.



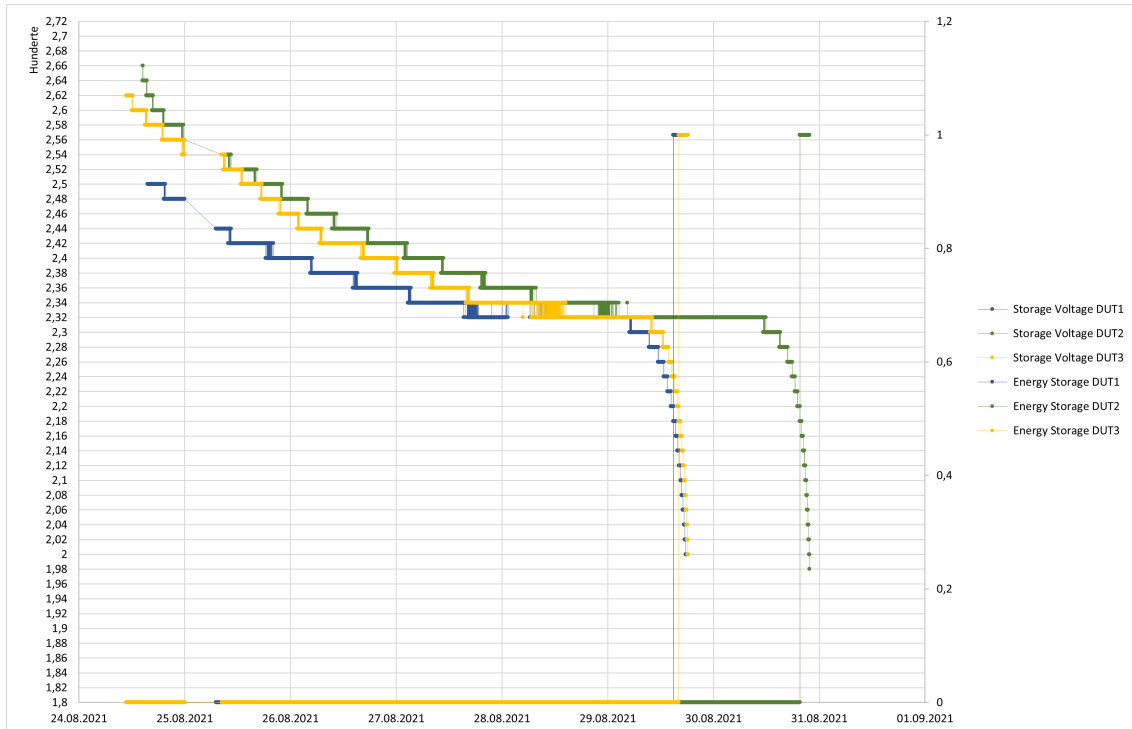
2 Exemplary values for STV and computed energy balance.

6.1.2 Energy Storage

Using its status bit "Energy Storage", the unit indicates that its long-term operation consumed more energy than it generated. The remaining charge level at this point is approximately 25%, which is why the device continues with full functionality while signaling a negative energy balance to the user. It is strongly recommended to regularly check the ES bit in order to recognize a discharge of the storage and

to prevent its progression by suitable measures (e.g. regular, short heating intervals outside of the standard operating times). If the energy storage continues to discharge and its voltage falls below a certain limit, then the unit automatically goes into the state of forced heating.

<u>Energy storage typical voltage values</u>	<u>Voltage [V] LTO</u>
Fully charged – for charge stop (bq25505 and USB)	2.8
Fully charged – for indicator bit	2.7
Normal operation	2.4 typical (2.0 ... 2.8)
Energy storage bit set when below	2.3
Forced heating starts when falling below	2.0
Forced heating ceases when rising above	2.4
Microcontroller turning off all loads and its own power when falling below	1.8
Microcontroller power-up (under hardware-control) when rising above	2.37
Battery spec HTC1450 (capacity / charge stop / discharge stop)	>500mAh / 2.8V / 1.5V



3 Illustration of battery discharge curves from different starting point and ES bit activation

7 Forced Heating MLR003R

Forced heating is defined as the state that the actuator assumes when it can no longer maintain normal operation due to the discharge of its internal energy store (Storage voltage level $<2V$). Instead, it takes a protective position in heating mode to avoid possible freeze damage. For this purpose, the actuator opens the valve to 50% or maintains the current position if it is more than 50%. The unit then deactivates itself into a state of minimal energy consumption: No radio or motor activities, local inputs are ignored. It remains in this state until the storage is recharged to a sufficient level by the thermoelectric generator. In this operating mode, the unit cannot be addressed neither by radio nor locally, and temperature fluctuations in the room will likely occur. As soon as sufficient charge level is available, the actuator stops the forced heating and resumes normal operation. Restoring the storage device to full charge requires full heating operation for several days, which is why this condition should be avoided by taking appropriate measures in advance (monitoring the ES bit, Slow harvesting).

7.1 Slow Harvesting

Only supported in MLR003RiEU61-07-2.0

8 Communication Profile MLR003RiEU61-07-1.1

<u>FPort Number</u>	<u>Type of operation</u>	<u>Payload length</u>	<u>Description</u>	<u>Comments</u>
0x00	MAC Commands	8 Bytes	RESERVED	
0x01	<ul style="list-style-type: none"> Valve position % mode Temperature setpoint mode (°C) with ambient or external temperature sensor 	Downlink: 6 Bytes Uplink: 11 Bytes	<ul style="list-style-type: none"> Actuator operation mode with valve position % only Self-regulation mode using the requested ambient setpoint temperature 	Strongly recommended to always use an external temperature sensor
0x02	Report REV Number, Hardware and Firmware Version	Downlink: () Uplink: 6 Bytes	Request REV Number, Hardware and Firmware Version	Only supported in MLR003RiEU6 1-07-2.0
0x03	Motor operating range	Downlink: 1 Byte Uplink: 1 Byte	Set/change motor operating range (mm) from default value 2,56mm	Only supported in MLR003RiEU6 1-07-2.0
0x04	LoRa Spread Factor	Downlink: 1 Byte Uplink: 1 Byte	Set/change LoRa spread factor from default value	Only supported in MLR003RiEU6 1-07-2.0
0x05	Slow Harvesting (SH) and Valve opening point detection OPD)	Downlink: 1 Byte Uplink: 1 Byte	Activate and report OPD, activate/deactivate Slow Harvesting	Only supported in MLR003RiEU6 1-07-2.0

8.1 FPORT 0x01 UPLINK: MLR003RiEU61-07-1.1 to Controller / Network Server

BYTE	BIT RANGE	SIZE	OFFSE T	ABB REV.	DETAILS
1	DB0.7...0.0	8	0	CVP	Current Valve Position % 0x00 ... 0x64 / 0 ... 100% Res = 1%
2	DB1.7...1.0	8	8	FSR V	Flow Sensor RAW Value °C 0x00 ... 0xFF / 0 ... 125.0°C Res = 0.5°C
3	DB2.7...2.0	8	16	FTM P	Flow TEMPERATURE Value °C 0x00 ... 0xFF / 0 ... 125.0°C Res = 0.5°C
4	DB3.7...3.0	8	24	ASR V	Ambient Sensor RAW Value °C 0x00 ... 0xFF / 0 ... 63.75°C Res = 0.25°C
5	DB4.7...4.0	8	32	ATM P	Ambient TEMPERATURE Value °C 0x00 ... 0xFF / 0 ... 63.75°C Res = 0.25°C
6	DB5.7	1	40		RESERVED
	DB5.6	1	41	ES	Energy Storage is low 1 = Battery is low
	DB5.5	1	42	HA	Harvesting 1 = Harvesting is active
	DB5.4	1	43	ASF	Ambient Sensor Failure 1 = Sensor Failure

	DB5.3	1	44	FSF	Flow Sensor Failure 1 = Sensor Failure
	DB5.2	1	45	RCE	Radio Communication Error 1 = Radio Loss
	DB5.1	1	46	RSS	Radio Signal Strength 0 = Normal Radio Signal (RSSI is greater than -100 dBm) 1 = Weak Radio Signal (RSSI is less than -100 dBm)
	DB5.0	1	47	ME	Motor 1 = Motor Error
7	DB6.7...6.0	8	48	STV	Storage Voltage V 0x00 ... 0xFF / 0 ... 5100mV Res = 20mV
8	DB7.7...7.0	8	56	ACC	Average Current Consumed 0x00 ... 0xFF / 0 ... 2550µA Res = 10µA
9	DB8.7...7.0	8	64	ACG	Average Current Generated 0x00 ... 0xFF / 0 ... 2550µA Res = 10µA
10	DB9.7	1	72	OFF	Operating Condition 0 = Device is in Normal Operation and is Active 1 = Device is in Mounting Position and OFF
	DB9.6	1	73	SFC	Storage Fully Charged 1 = Fully Charged
	DB9.5	1	74		RESERVED

	DB9.4	1	75	REF C	Reference Run Completed 1 = Successfully Completed
	DB9.3...9.2	2	76		RESERVED
	DB9.1...9.0	2	78	UM	User Mode As set by the last received Downlink (DB3.3...3.2)
					0b00 Valve Position %
					0b01 RESERVED
					0b10 SP Ambient Temperature °C
					0b11 RESERVED
11	DB10.7... 10.0	8	80	UV	User Value according to User Mode As set by the last received Downlink (DB0.7...0.0) VALVE %: 0x00 ... 0x64 / 0 ... 100% Res = 1% AMB TEMP: 0x00 ... 0x50 / 0 ... 40°C Res = 0,5°C

8.2 FPORT 0x01 DOWNLINK: Controller / Network Server to MLR003RiEU61-07-1.1

BYTE	BIT RANGE	SIZE	OFFSET	ABBREV.	DETAILS	
1	DB0.7 ...0.0	8	0	SPV	Set Point Value according to User Mode VALVE %: 0x00 ... 0x64 / 0 ... 100% Res = 1% AMB TEMP: 0x00 ... 0x50 / 0 ... 40°C 0x00 = Default = 0x28 = 20°C Res = 0,5°C	
2	DB1.7 ...1.0	8	8	RT	Room TMP from RCU °C 0x00 ... 0xA0 / 0 ... 40°C 0x00 = No Room TMP provided Res = 0,25°C	
3	DB2.7 ...2.0	8	16	SSV	Set Safety Value according to safety mode AMB TEMP: 0x00 ... 0x50 / 0 ... 40°C 0x00 = Default = 0x28 = 20°C Res = 0,5°C VALVE %: 0x00 ... 0x64 / 0 ... 100% Res = 1%	
4	DB3.7	1	24		RESERVED	
	DB3.6 ...3.4	3	25	RCI	Radio Communication Interval 0b000 = Default = 10 minutes	
					0b000	10 minutes
					0b001	5 minutes
					0b010	60 minutes

					0b011	120 minutes
					0b100	480 minutes
					0b1zz	RESERVED
	DB3.3 ...3.2	2	28	UM	User Mode 0b10 = Default = SP Ambient Temperature	
					0b00	Valve Position %
					0b01	RESERVED
					0b10	SP Ambient Temperature °C
					0b11	RESERVED
	DB3.1 ...3.0	2	30	SM	Safety Mode 0b00 = Default = SP Ambient Temperature	
					0b00	SP Ambient Temperature °C
					0b01	RESERVED
					0b10	Valve Position %
					0b11	RESERVED
5	DB4.7 ...4.4	4	32	FSOC	Offset Compensation Flow Sensor °C -8°C ... +7°C	
					0x00	+5°C (default)
					0x01	+1°C
					0x02	+2°C

					0x03	+3°C
					0x04	+4°C
					0x05	+5°C
					0x06	+6°C
					0x07	+7°C
					0x08	-8°C
					0x09	-7°C
					0x0A	-6°C
					0x0B	-5°C
					0x0C	-4°C
					0x0D	-3°C
					0x0E	-2°C
					0x0F	-1°C
	DB4.3 ...4.0	4	36		RESERVED	
6	DB5.7	1	40	REF	Do Reference Run now Default = 0	
	DB5.6 ...5.5	2	41	GAIN	Proportional Controller Gain 0b00 = Default = 3	
					0b00	3
					0b01	4

					0b10	1
					0b11	2
	DB5.4 ...5.0	5	43		RESERVED	

8.3 FPORT 0x02 REV Number, Hardware and Firmware Version MLR003R

Only supported in radiator product series MLR003RiEU61-07-2.0.

8.4 FPORT 0x03 Motor operating range MLR003R

Only supported in radiator product series MLR003RiEU61-07-2.0.

8.5 FPORT 0x04 LoRa Spread factor MLR003R

Only supported in radiator product series MLR003RiEU61-07-2.0.

8.6 FPORT 0x05 Slow Harvesting SH and Valve Opening Point Detection OPD MLR003R

Only supported in radiator product series MLR003RiEU61-07-2.0.

5. Click Submit
6. Wait for Save and Apply to go red, and then click it

9.3 Pairing the Device with a Room Controller or Gateway

Devices will be accompanied with a spreadsheet containing the following information:

- Device EUI
- Join EUI
- Application Key

The Device EUI is unique to the device and allows identification and communication via LoRaWAN.

The Application Key is randomly generated and the password to ensure secure communication.

To pair a device to a MultiTech gateway:

1. In a web browser, navigate to the gateway IP address
2. Login to the gateway
3. (Only needs to be done once:)
LoRaWAN, Network Settings, Join Delay 5 seconds
LoRaWAN, Network Settings, Max Datarate 5 – SF7BW125
4. LoRaWAN, Key Management, click Add New
5. For each device, enter the following details, and then click OK:
Dev EUI (available in the spreadsheet)
App EUI (available in the spreadsheet)
App Key (available in the spreadsheet)
Class: A
Device Profile: LW102-OTA-EU868
Network Profile: DEFAULT-CLASS-A
6. Click Submit
7. Wait for Save and Apply to go red, and then click it

9.4 Mounting Position and OFF

In mounting position, the plunger inside the product's valve adaptor is fully retracted, so that the unit can be easily attached to a circulation valve. In mounting position, the product is OFF, preserving the charge of the internal energy storage device. This makes it the preferred mode for shipping and storing.

How to enter mounting position from normal operation:

- If the unit is attached to a valve, remove it
- Hold the pen magnet to the micropelt logo on the product's cover until a beep sounds
- The unit will fail the reference run and consequently end up in mounting position

Upon delivery, all new units are in mounting position.

9.5 Attaching and Activating a unit

Before attempting to attach a unit to a valve, be sure it is in mounting position (refer to the above section).

Check the target valve for contamination and leakage. If the valve requires it, do cleaning or service. Then, place the aluminum connector of the product against the valve and secure it by using the ring nut.

Should the target valve not be of type M30 x 1.5, an adaptor is required.

Once the unit is securely attached to the valve,

- Briefly tap the pen magnet on the micropelt logo on the product's cover
- The radio establishes a link to the gateway → upon successful completion, a double-beep sounds
- The motor performs a reference run → upon successful completion, a triple-beep sounds
- The unit is now active

Activation only works from mounting position. If performed during normal operation, the product will not show any reaction.

9.6 Reset (from Normal Operation only)

The MLR003FiEU61-12-1.1 RESET function allows access to mounting position. It is also useful to restore correct operation should a malfunction occur.

To RESET the device,

- Hold the pen magnet to the micropelt logo on the product's cover until a beep sounds
- The internal microcontroller will reset and restart
- If the device is mounted on a valve, it will activate

If the device is unmounted, it will go into mounting position and switch OFF

9.7 No Reset from Mounting Position

9.8 Removal from the Valve

Unscrew the ring nut from the valve and RESET the device. It will move to mounting position and switch OFF.

9.9 Temperature Control Loop

To obtain an estimate of the ambient temperature, the device measures the flow temperature every 5 minutes and performs a moving average across the last 30 minutes. It then performs the following computation:

$$\frac{\text{Ambient Sensor Raw Value}^{2.2}}{\text{Flow Sensor Raw Values Moving Average}^{1.2}}$$

Having established an estimate of the ambient temperature, the device then compares this estimate to the ambient temperature requested by the user. If they are the same, or if the ambient temperature is already moving towards the requested temperature, the device does not move the motor. Otherwise, the device applies a Proportional Controller Gain algorithm to compute the motor movement:

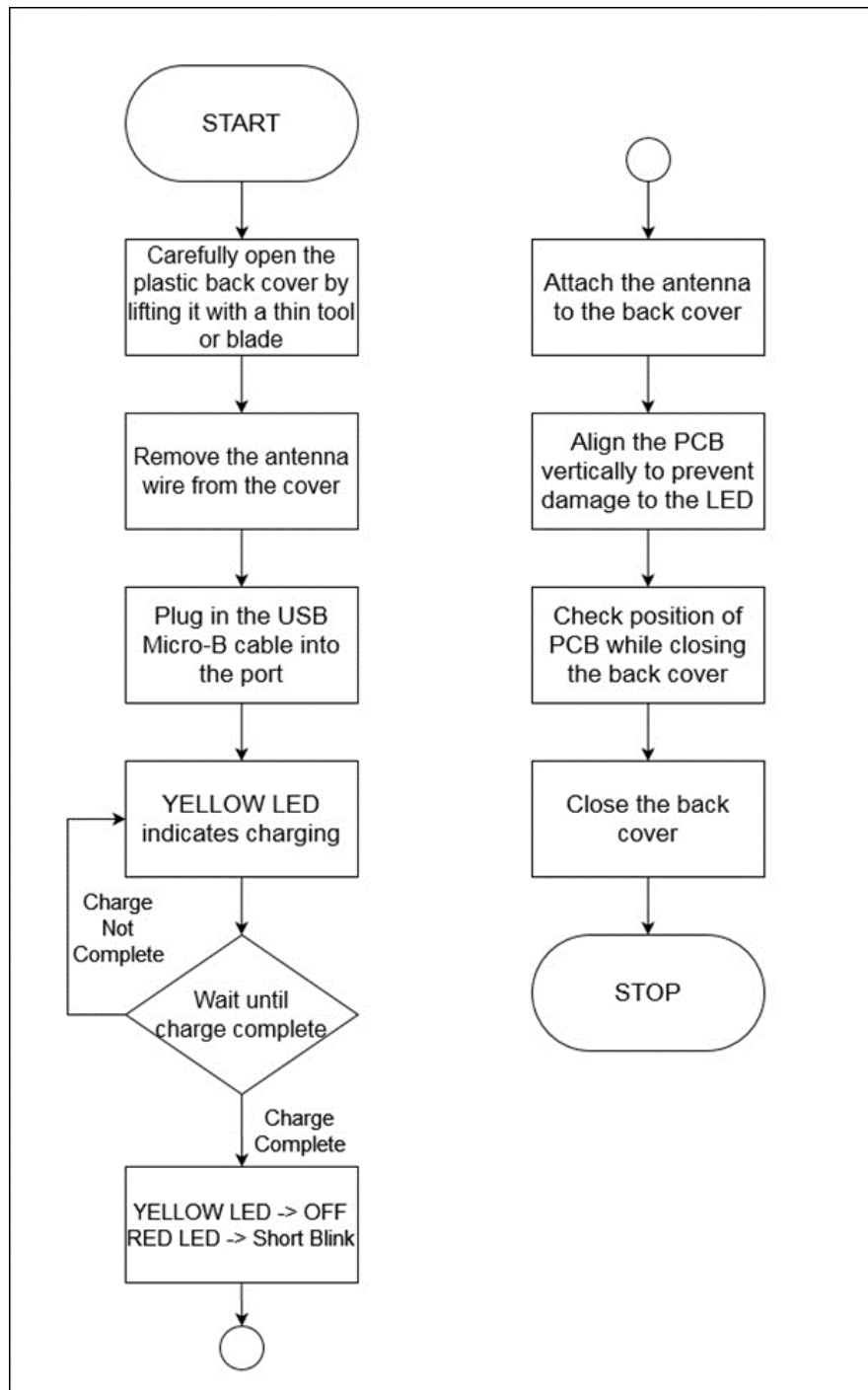
$$(P * \text{Temperature Difference} * 4) \%$$

The default value of P is 3. It can be modified via the downlink packet (Section 7.2).

9.10 Antifreeze

The antifreeze function prevents damage to the pipes. Below 6°C at the integrated valve side temperature sensor, the valve opens to 95%. The 6°C is an absolute temperature, any user-offset is ignored.

9.11 Battery Charging Flow Chart



10 Performance Data MLR003RiEU61-07-1.1

Parameter	Range
Ambient operating temperature	0 to 40°C, max 70% rH
Flow pipe temperature	75°C max
Transportation & storage temperature range	-20 to +65°C, max 70% rH
Dimensions (LWH)	83 x 60 x 64 mm (63 x 60 x 64 without valve connector)
Weight	280 g (not including packing)
Operation at high altitude	Max 2000 m / 6500 ft above sea level
Max pin stroke (calibration range)	> 5.5 mm
Operating pin stroke (0-100%)	2.56 mm typical
Pin Stroke Resolution	Steps of 1%
Adjustment speed	0.727 mm/s typical
Stall force	100N
Noise level	< 35 dB(A) @ 70 N load
Radio Communication Interval (default)	10 minutes
Radio Communication Interval during Installation Cycle	10 seconds for 5 minutes
Radio Communication attempt Interval (after join fail or 6 consecutive communication fails)	3 * 10 seconds Then 2 minutes Then 60 minutes

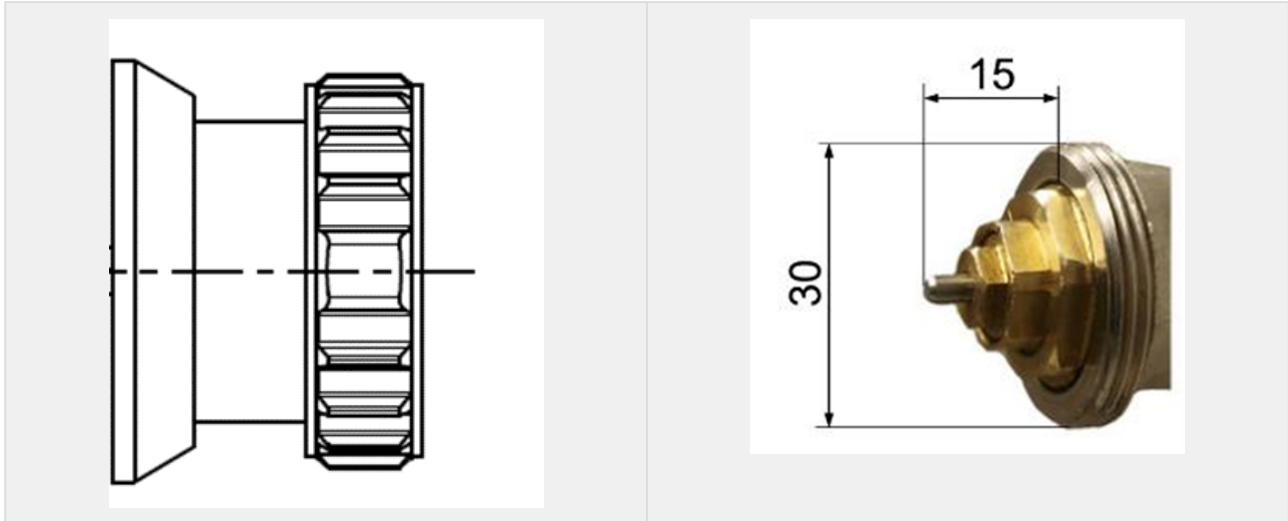
Valve protection and Auto-off when active but not installed on valve body	Every 6 weeks: Execute run-in sequence. On pass return to previous position. On fail enter mounting position, communicate OFF and shut down.
Antifreeze	Valve side sensor $\leq 6^{\circ}\text{C}$
Safe position default	Depending on Safety Mode: Either default temperature setpoint Or default valve position Default: Setpoint Ambient 20°C
Operating Modes	Valve Position [%] Target Ambient Temperature ($^{\circ}\text{C}$) Default: Valve Position
Accuracy of internal valve side temperature sensor	$\pm 0.5^{\circ}\text{C}$
Accuracy of internal ambient temperature sensor	$\pm 0.5^{\circ}\text{C}$
Default offset of internal valve-side temperature sensor	+5K (Added to the raw sensor value FSRV)
Energy storage	LTO (Nominal 500mAh)
Energy generation minimum requirement	90 days / year @ 45°C flow pipe temperature
Battery voltage flag (ES)	Battery-low flag will be set when battery voltage drops below 2.3V

Conformity Radio Radio EMC EMC EU Human Exposure Product safety	CE: EN300220-2V3.1.1 & EN300220-2V3.2.1 & EN300220-1V3.1.1 EN301489-1 V2.2.3 / -3 V2.1.1 EN55014-1 / -2 EN62479 EN60335
Radio specification	868.0 - 868.6 MHz, 14 dBm SF7

11 Mechanical Interface to circulation valve body MLR003R


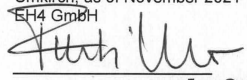
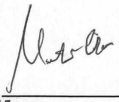
Mechanical Interface to circulation valve body

The MLR003R series of products is designed to mount onto an M30 x 1.5mm valve.



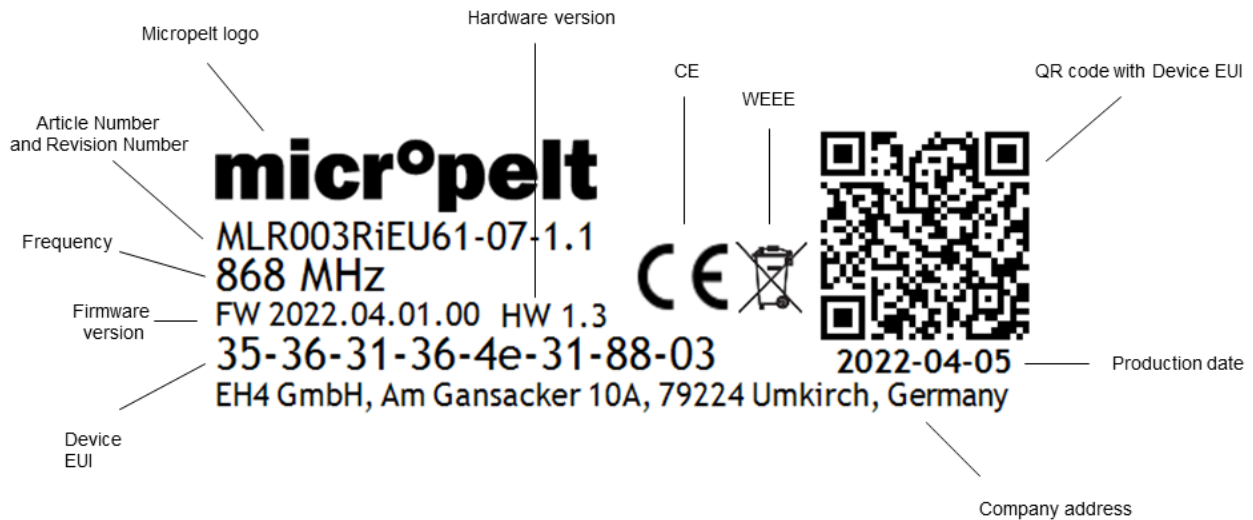
Several other valve types are served by metallic adapter pieces.

12 CE Conformity MLR003RiEU61-07-1.1

micropelt	
Declaration of Conformity	
According to EU regulation EU 2019/1020 on market surveillance and product conformity	
Manufacturer:	EH4 GmbH (Brand Micropelt)
Address:	Am Gansacker 10a, 79224 Umkirch, GERMANY
We declare the conformity of the following product:	
Product Description:	Wireless heating radiator actuator/thermostat powered by thermal energy harvesting. LoRaWAN 868MHz
Product Type(s):	MLR003 & MLR003F
Production Year(s):	2021 ff.
With regard to its design and construction and in the form, we first introduced it to the market it is in conformity with the essential health and safety requirements of the Radio Equipment Directive:	
Radio Equipment Directive (RED) ETSI EN 300 220-2 V3.2.1 (2018-06) ETSI EN 300 220-2 V3.1.1 (2017-02)	
EMC ETSI EN 301 489-1 V2.2.3 clause 8 & 9 (add. V1.9.2) ETSI EN 301 489-3 V2.1.1 (add. V1.6.1) EN 55014-1:2017 (add. EN 55014-1:2006+A1:2009+A2:2011) EN 55014-2:2015	
Human Exposure EN 62479: 2010	
Product Safety IEC 60335-1: 2010, COR1:2010, COR2:2011, AMD1:2013, COR1:2014, AMD2:2016, COR1:2016 EN 60335-1:2012 + AC:2014 + A11:2014 + A13:2017 + A14:2019 + A1:2019 + A2:2019	
Battery Safety EN 62133-2:2017 (add. AMD1:2021) Battery Transport UN38.3	
	
Umkirch, as of November 2021	
 	
Fritz Volkert, CEO	micropelt Martin Schmidt, RND
EH4 GmbH Am Gansacker 10a 79224 Umkirch www.micropelt.com	

13 Labeling MLR003R

13.1 Product Label



<u>What</u>	<u>Requirement</u>
Product type	On Label
Version number REVn.n	On Label
Date of production	On Label
Hardware version	On Label

Firmware version	On Label
LoRaWAN frequency	On Label
Device EUI (16 digits)	On Label
Join EUI (16 digits)	In Spreadsheet
Application Key (32 digits)	In Spreadsheet (Secret)
Country of Origin	On Label
Address	On Label
Micropelt Logo	On Label

13.2 NFC Tag Label

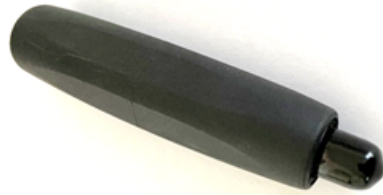
Warranty void
if removed



4 QR code with NFC Tag

14 Accessories MLR003

14.1 MLR003-KEY Magnetic switch



5 Pen-shaped magnet required for activating and deactivating the device (see Section 12.)